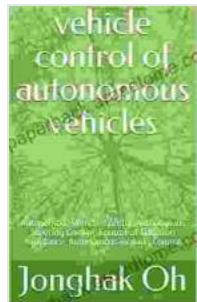


Vehicle Control of Autonomous Vehicles: A Comprehensive Guide to Mastering Autonomous Driving

As the world rapidly embraces the era of autonomous vehicles, mastering vehicle control becomes paramount for engineers, researchers, and industry professionals. This comprehensive guidebook delves into the fascinating realm of vehicle dynamics, actuator control, and advanced algorithms, equipping readers with the knowledge and skills to navigate the future of transportation.



vehicle control of autonomous vehicles: Autonomous Vehicle Control, Autonomous Steering Control, Control of Collision Avoidance, Autonomous Braking Control (tech research)

5 out of 5

Language : English

File size : 10957 KB

Text-to-Speech : Enabled

Screen Reader : Supported

Enhanced typesetting : Enabled

Print length : 171 pages

Lending : Enabled

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Chapter 1: Vehicle Dynamics for Autonomous Vehicles

1.1 Fundamentals of Vehicle Dynamics

- Newton's Laws of Motion applied to vehicle systems

- Kinematic and dynamic models of vehicle behavior
- Understanding tire-road interactions and friction forces

1.2 Modeling and Simulation Techniques

- Developing accurate mathematical models for vehicle dynamics
- Using simulation tools to analyze vehicle performance
- Validating models through experimental testing

Chapter 2: Actuator Control for Autonomous Vehicles

2.1 Types of Actuators in Autonomous Vehicles

- Electric motors for propulsion and steering
- Hydraulic systems for braking and suspension control
- Pneumatic systems for gear shifting and clutch operation

2.2 Control Techniques for Actuators

- PID control for basic actuator operation
- Model-based control for improved performance
- Advanced control algorithms for fault tolerance and optimization

Chapter 3: Advanced Algorithms for Autonomous Vehicle Control

3.1 Path Planning and Trajectory Optimization

- Algorithms for generating safe and efficient vehicle trajectories
- Optimization techniques to minimize energy consumption and travel time

- Integration of environmental information for real-time decision-making

3.2 Model Predictive Control for Autonomous Vehicles

- Principles of Model Predictive Control (MPC)
- Formulating optimization problems for vehicle control
- Implementing MPC algorithms in real-time environments

Chapter 4: Case Studies and Applications

4.1 Autonomous Vehicle Design and Development

- Case study on designing and building an autonomous vehicle prototype
- Overview of industry best practices and safety standards
- Challenges and opportunities in autonomous vehicle development

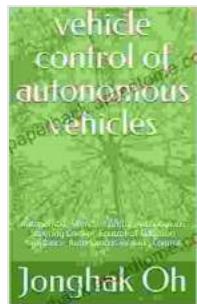
4.2 Applications in Transportation and Logistics

- Autonomous cars for passenger transportation
- Autonomous trucks for long-haul freight transport
- Autonomous drones for package delivery and aerial surveillance

This comprehensive guidebook provides a solid foundation for understanding the intricate world of vehicle control for autonomous vehicles. By mastering the principles of vehicle dynamics, actuator control, and advanced algorithms outlined in this book, readers will gain the expertise needed to design, develop, and deploy safe and efficient autonomous vehicles. As the industry continues to evolve, this guide will

serve as an invaluable resource for engineers, researchers, and visionaries shaping the future of transportation.

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